

Danielle Mustillo

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<https://danielle-mustillo.github.io>

EDUCATION

Bachelor of Software Engineering – McGill University 2012-2016

- GPA: 3.73
- \$500 scholarship – The Dean's Honour List (top 10% of Faculty)
- 99% final grade - Introduction to Computing (Java)
- Offered \$1000 scholarship to identical program at Concordia University.

WORK EXPERIENCE

Coop Intern – Ericsson Canada – 4 Months 2016

- Developed Test Automation and Continuous Integration tools
- Python with Jinja templating, YAML files
- Setup reverse proxy w/ Apache Server to get around CORS for HTTPS REST queries
- Frontend JavaScript (jQuery, Vue.js), CSS, HTML: demoed these for users and designed to be interactive (debouncing, asynchronous, etc).
- Java, IntelliJ, Jenkins, Sonar (code coverage), Git, Gerrit Code Review, Vagrant, Unix, CentOS, Red Hat Linux, Ansible.

Coop Intern – Ericsson Canada – 4 Months 2015

- Developed IoT (Internet of Things) framework
- Java, Restful services, Gstreamer, Raspberry Pi
- Developed JavaScript/AngularJS/JQuery(testing) WebRTC webpage for P2P
- Created CoAP-like protocol for communication
- Interconnected IMS core with application (WCG) via REST, SRTP, SCTP/DTLS, UDP, TCP
- Developed target deployments through Bash & Python
- Used SCRUM, JUnit, Eclipse, Maven, Jenkins, Sonar, Ubuntu

Engineering Intern - Mannarino Systems & Software Inc. – 8 Months 2014

- DO-178-B trained
- Verification of flight production SW (in C).
- Test environment in Python, iSystem debugger for breakpoints.
- Modified Coverage/Decision Coverage and End-to-End testing of SW.

IT Student – Canadian Revenue Agency – 3 Months 2013

- Used Powershell scripts to automate remote admin tasks
- Fixed varying hardware issues (printers, scanners, software, etc).

TECHNICAL PROJECTS

- **Personal Website**
 - Jekyll (Ruby) with HTTPS for static webpages
 - Creative Commons
- **Machine Learning in LabView**
 - Developed a neural network in Labview to learn accelerometer positioning
 - Customized the net with bias, different training amounts, different number of layers, etc.
 - Unit tested these nets
- **Investment Portfolio Tracker**
 - Python, JavaScript, CSS, HTML with Libraries
- **Research**
 - SQL, Matplotlib & Python to interpret relations between data sets
 - Some Excel and formulas
- **Password Cracker**
 - OpenCL run on AMD R9 290 card
 - Multi-platform run on CPU and GPU to compare (10-20x speedup)
 - I had adapted the MD4 hashing algorithm for OpenCL (you can't use malloc for example)
- **Packet Sniffer**
 - Processes raw byte-code packets in C and extracts IPv4 headers and content data.
 - Attempted to run in on RJ-45 connector soldered to board, but chip not fast enough for real time processing (darn)
- **File System**
 - Functional filesystem with implemented inodes
 - Used Linux FUSE (Filesystem in Userspace) to expose APIs
 - Relatively complete support of Vim & Nano in this FS
- **Vector Calculator in Android**
- **Arduino Wall Follower**
 - Implemented low pass, median, out of bounds rejection filter to process real time data
 - Used ultrasonic sensors & motors to do this (low cost)
 - Developed connection algorithm to Python computer program to output CSV data for processing
- **Java Light Racer**
 - Build process using Ant
 - Used I/O streams, JUnit and created UML and Use Case Diagrams
 - Black box testing, white box testing, SOLID principles.
- **NXT Lejos Robot**
 - Developed search, pickup, drop off and obstacle avoidance algorithm
 - Concurrent Programming with threads (synchronization, dependency resolving, etc).
 - Data handling (P2P I/O streams between two different Lejos)
 - Event driven programming (listeners, timers, etc), Exception handling
 - Robotic concepts: Navigation, obstacle avoidance, odometry, odometry correction, search and rescue, localization.